Installation Procedure: D5/D7 MG MCC Installation Overview D5/D7 MG MCC Document number: 47706838 Release date: 06-2015 **AUX, Emergency and Combined MCC Electrical connection box Jumper settings** CAN2 speed 32C / 250kBd (<200 meter between units) (default) CAN2 speed 8C / 50kBd (<900 meter between units) (slower response times) The jumpers factory setting show below. If application requires additional sensors then change jumper settings. Optional with remote panel Remote Panel jumper settings*3 MCU jumper settings*1 Connect to PC Tool DriveConfig*4 MCU jumper settings*1 Switch for backlight **Connect to external MODBUS system** To use a switch to alternate between adjusted brightness and 100% brightness connect it as following: VOLVO PENTA Switch between PC tool and MODBUS via MCU menu. IIELD COM AINT AINT AINT AINT AING AING AING AING AING AING AING AINR AINR B16 B17 B19 B111 B112 B113 Horn Reset Reset STOP Horn Reset Reset STOP Horn Reset STOP Communication is connected here. Category A + = -Category B Standard RS232 max length 10 m. Use a RS232 to RS485/422 converter to extend length to 200 or 900 (set in MCU menu) Use cables Category E CAN L •••••••• Aux. I/O equipment Comap RPU connection (Redundant Protection Unit) Refer to InteliDrive user guide • SDU jumper factory settings*2 Aux. I/O equipment Relay connection (24 V Only) AUX and combined AUX/EME is set: Input Connections (24 V only) **Use cables Category A to all relay contact connections** ON OFF **Use cables Category A** A6+ A6- Spare to use. EME is set: X1 Harbour mode indication X2 Local mode indication S3 S4 S5* Overspeed shutdown can not be switched off. * Should be ON if used as emergency stop. <u>수</u>부의 | A1 | 0 이 A2 0 0 A3 0 0 Remote Panel Jumper settings*3 A4 0 0 Remove the cover to access termination jumper settings. A5+ 0 0 A1 to A8 Internal functions only. Remote panel CAN2 bus is terminated with 120 Ohm resistor ○ O A5- O O inside the unit. If **one** Remote Panel is used, leave the jumper closed (default). If **more than one** Remote Panel is installed to each driveline, +9 A7- O O the termination jumper need to have a removed (open) jumper X9 Ready to take load on all units except for the last one in the chain. A8+ O O This last unit should have a closed jumper setting. -8A C X10 Ready to start engine 0 9 B6 0 0 Inputs external binary X11 Engine running indication 0 9 B7 0 0 Termination jumper 0 9 B8 0 0 X12 [Internal function] SDU jumper settings*2 Emergency Stop.. B9 00 Start blocking... X13 [Internal function] 9 B10 O O X14 [Internal function] ♀¦3 B11 O O Remote Start.. **3** B12 O O Blackout start...... 9 B13 O O ⚠ Note! Internal functions B14— The figure above shows the board with the cover removed. 9 B14 O O 0 0 DA 0 0 **Remote Panel Software update** 0 0 EA 00 0 0 KA 00 Ground should be applied Spare relay * 0 0 LA 0 0 by the shortest cable possible 0 0 S1 0 0 with a diameter of equal to or 0 0 S2 0 0 greater than 2.5 mm² 0 0 83 0 0 0 0 84 0 0 Pin 15,16 **3** 85 0 0 Relays X1 - X16 Connect to 0V if External Stop switch S5*-X15 and X16 shall 0 0 SR 0 0 3. Normally Closed (NC) be activated. 0 0 1 00 2. Normally Open (NO) Remote Panel application software is uploaded automatically O 9 L 1 O O from MCU during power up. Base software (firmware) do not 0 1 00 normally need to be downloaded. If future firmware updates are required, the unit can be reprogrammed. 0 9 7 2 00 Connect to + at the 1. Power off the unit. back of the remote panel. 2. Remove the rubber plug and temporarily remove 0 0 12 00 the boot jumper. Connect to - at the 0 0 0 3. Connect programming cable to RS232 and download firmware back of the remote panel. (refer to VPPN MCC site for details) **Secondary Battery (Backup)** 0 0 3 0 0 **Engine connection box** 4. Power off the unit. * Use 10 kOhms for broken 0 0 41 0 0 Use cables Category C 5. Put back the boot jumper and the rubber plug. wire detetion. 0 0 42 0 0 0 0 65 0 0 The jumper for S5 needs to **Remote Panel CAN2 Connection** be set to enabled. 0 0 66 00 The D-Sub (CENTRAL UNIT interface) uses the following pins: 0 0 82 0 0 00 1 00 CAN H - 5 — **Primary battery connection** Electrical and combined Electrical /Air starter Cable for DriveConfig/DriveMonitor*4 **Use cables Category D** The Connector used for PC Tool (DriveConfig/DriveMonitor) onnect + battery cable here. has the following wiring: Bolt size M10. ightening torque 15 ±3Nm Connect - battery cable here. Bolt size M8. ightening torque 12 ±1Nm VOLVO PENTA Relays marked with "Spare Relay" are allowed to use as desired. Activate by OV. Note that it may require special settings to make

Components and Cables

Components

3818237

Remote Panel

3888244

0 0 A1 0 0 0 0 A2 0 0

0 0 A4 0 0

0 0 A5- 0 0

0 0 A7- 0 0

0 0 B6 0 0

0 0 B7 0 0

0 0 B8 0 0

0 0 B11 0 0

0 0 EA 00

0 0 KA 0 0

0 0 LA 0 0

0 0 84 0 0 0 0 85 00

0 0 1 00

0 0 1 0 0

0 0 1 0 0 0 0 12 00

0 0 0 2 0 0 0 0 0 2 0 0

0 0 3 0 0

0 0 82 0 0

Input Connection

3842883

00

10 0

A3 0 0

A5+ O O

A7+ O O

A8+ O O

A8- O O

B9 O O

B10 O O

B12 0 0

B13 O O

B14 0 0

DA O O

S1 0 0 S2 00 S3 O O

SR O O

41 0 0

42 0 0

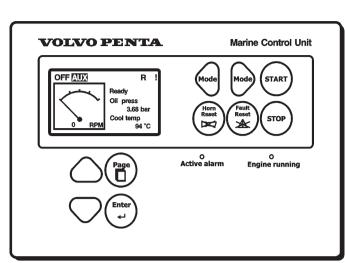
65 00 66 00

Relay Connection

Part no.

3818362

VOLVO PENTA

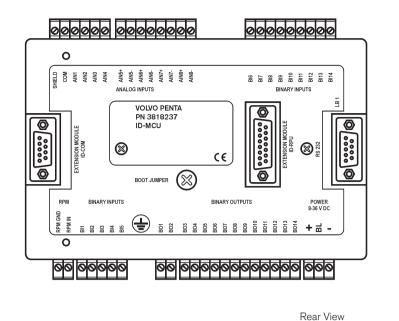


MCU Marine Control Unit Front View

Remote Panel

Front View

Mode START



POWER 8-36 V DC + 🖬 -

Rear View

SHUTDOWN

21350693

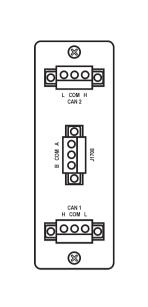
SDU - Shutdown Unit

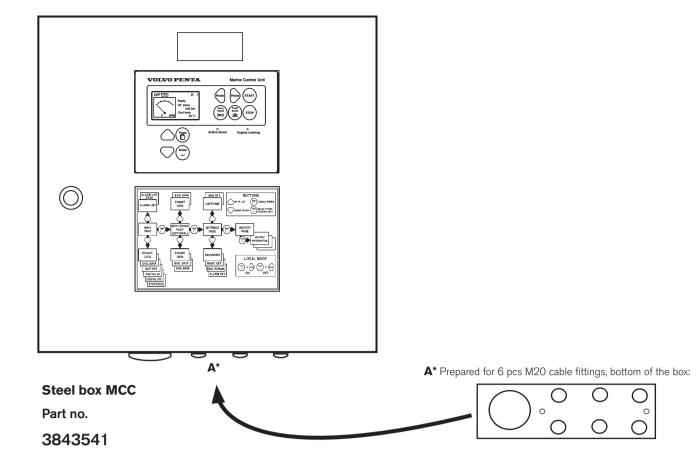
Spare part no. (includes reference to calibration document)

Part no.

3819845

ID-COM Part no. 3818364 ID-COM is only used with Remote Panel





MCU / Remote Panel Engine Data

Indicator	AUX	EME	Combined
Engine Speed	x	X	X
Oil Press	X	X	X
Oil Temp	X	X	X
Coolant Press.	X	X	X
Coolant Temp	X	X	X
Fuel Press.	X	X	X
Primary battery voltage	X	X	X
Sec. battery voltage	X	X	X

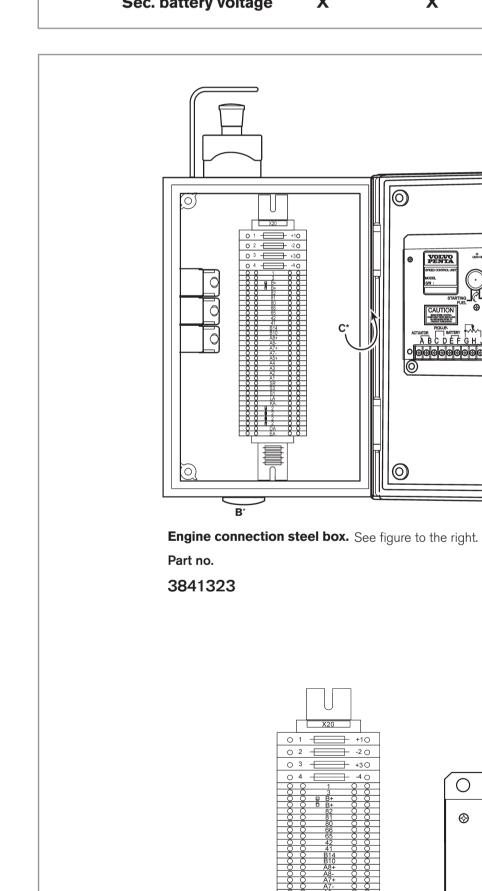
TRYO CHROLL THE SOLL CONSTRAINS

VOLVO PENTA

Part no.

A B C D E F G H J K L M N P

ESD 5500 GAC Speed Control unit (Optional)



Relay kit

Part no.

3885261

Input connection

Part no.

22451011

Cables

 \circ

0 0 0



MCC Connection cable

Category A Terminal block / relay connections

Crosscut area minimum 1,5 mm2 (16 AWG) type approved low voltage (30 V or more) ship cable, Max 50 meters (164 ft)

Category B CAN communication. Shielded, pairtwisted

Crosscut area min. 0,25 mm2 (23 AWG) 120 Ohm nominal impedance, Maximal attenuation (at 1 MHz) 2 dB / 100 m (328 ft), Max 900 meters (2953 ft) Nominal Velocity of Propagation min. 75% (max. 4,4 ns/m)

Category C Secondary Battery

Crosscut area 2,5 mm2 (13 AWG) type approved low voltage (30 V or more) ship cable, Max 30 meters (98 ft)

Category D Battery cables

Refer to Installation manual D5-D16 Publ. no: 47704151 for dimensions.

RS232: Use signal RS - TS twisted cable (Max. 10 meter / 32.8 ft)

Category E RS232 / MODBUS. Shielded, pairtwisted

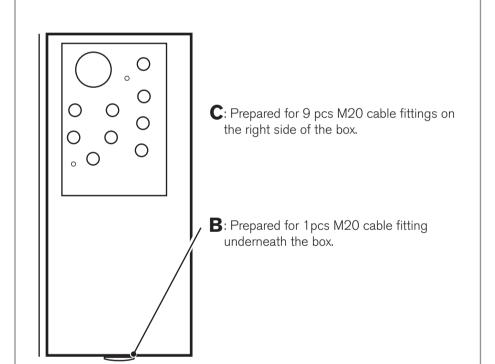
RS485/422: Less than 40 meters (131 ft): Crosscut min. 0,75 mm2, (18 AWG) 120 Ohm impedance, Max. attenuation (at 1 MHz) 1,7 dB / 100 m (328 ft)

RS485/422: Longer than 40 meters (131 ft): Drain wired, crosscut min. 0,75 mm2 (18 AWG) 120 Ohm impedance, Max. attenuation (at 1 MHz) 1,7 dB / 100 m (328 ft)

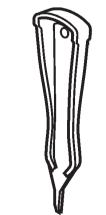
Prepared for M20 cable fittings

B* & C* M20 Cable fittings

Engine connection steel box



Input Connection Tool



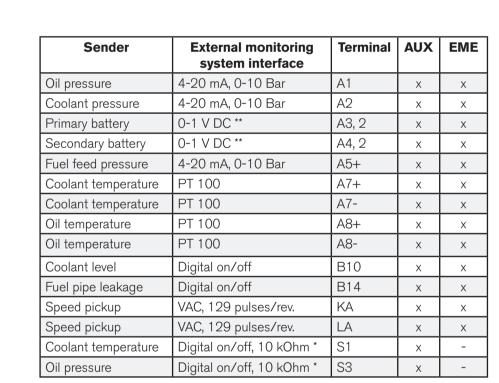
Tool Included in Steel boxes

Input Connections Bobtail (none MCC installations)

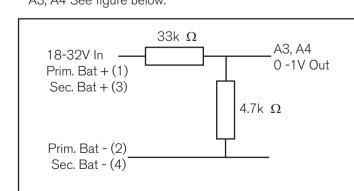
External monitoring system interface

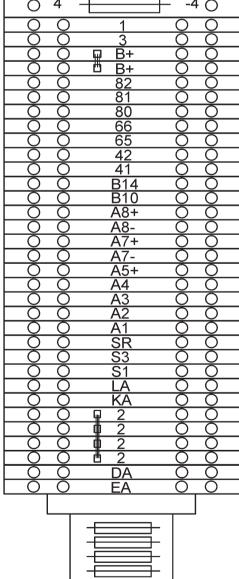
Use cables Category A

▲ NOTE! SD and alarm system must be configured according to engine Technical Data.



* Prepared for broken wire detection. (S1 & S3) ▲ NOTE! No shutdown unit or MCU included





X20

0 2 -2 0

** A3, A4 See figure below:

